

Anti-roll bar equation:

$$\frac{d\theta}{dt} = 1/l_b \cdot [w_{r1} - p \cdot l_y - p \cdot l_c + q \cdot l_x - w] - 1/l_b \cdot [w_{r2} + p \cdot l_y + p \cdot l_c + q \cdot l_x - w]$$

Front right unsprung mass vertical movement (wheel number one):

$$m_{rs1} \cdot w_{r1} = m_{rs1} \cdot g + k_{n1} \cdot x_{n1} - k_{s1} \cdot x_{s1} - r_{s1} \cdot [w_{r1} + q \cdot x_1 - p \cdot y_1 - w] - 1/l_b \cdot \left[\frac{d\theta}{dt} \cdot r_{12} + \theta \cdot k_{12} \right]$$

Front left unsprung mass vertical movement (wheel number two):

$$m_{rs2} \cdot w_{r2} = m_{rs2} \cdot g + k_{n2} \cdot x_{n2} - k_{s2} \cdot x_{s2} - r_{s2} \cdot [w_{r2} + q \cdot x_2 - p \cdot y_2 - w] + 1/l_b \cdot \left[\frac{d\theta}{dt} \cdot r_{12} + \theta \cdot k_{12} \right]$$

Sprung mass roll movement:

$$I_p \cdot p = \Sigma (\text{torques from vertical forces at the unsprung masses}) - \Sigma (\text{torques from transversal forces at the unsprung masses}) + I_q \cdot q \cdot r - I_z \cdot q \cdot r + [2/l_b \cdot (l_y + l_c)] \cdot \left[\frac{d\theta}{dt} \cdot r_{12} + \theta \cdot k_{12} \right]$$

Sprung mass vertical movement:

$$m_s \cdot w = m_s \cdot g + (\text{vertical forces at the unsprung masses}) + m_s \cdot u \cdot q - m_s \cdot v \cdot p + [2 l_y / l_b] \cdot \left[\frac{d\theta}{dt} \cdot r_{12} + \theta \cdot k_{12} \right]$$

